EAST Search History

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
L1	0	(contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and (sens$3 detect$3 monitor$3 measur $3) near2 (movement rotation angle shaft) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 10:51
L2	1	(contactless contact-less) adj3 power adj3 (transmission transmitting convert$3) and (sens$3 detect$3 monitor$3 measur $3) near2 (movement rotation angle shaft) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 10:53
L3	3	(contactless contact-less) adj3 power adj3 (transmission transmitting convert$3) and (sens$3 detect$3 monitor$3 measur $3 control$4) near2 (movement rotation angle shaft) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:05
L4	55	((contactless contact-less) adj3 power adj3 (transmission transmitting convert$3) ((inductive magnetic) adj2 coupl$3) ((rotatory rotational) adj2 (convert$3 transform$3))) same (sens$3 detect$3 monitor$3 measur$3 control $4) near2 (mov$3 movement rotation rotational angle angular shaft) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:07

L5	10	((contactless contact-less) adj3 power adj3 (transmission transmitting convert$3) ((inductive magnetic) adj2 coupl$3) ((rotatory rotational) adj2 (convert$3 transform$3))) same (sens$3 detect$3 monitor$3 measur$3 control $4) near2 (mov$3 movement rotation rotational angle angular shaft) same (static stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor rotary) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:11
L6	11	((contactless contact-less) adj3 power adj3 (transmission transmitting convert$3) ((inductive magnetic) adj2 coupl$3) ((rotatory rotational) adj2 (convert$3 transform$3))) same (sens$3 detect$3 monitor$3 measur$3 control $4) near (position movement rotation angle shaft) same (static stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor rotary) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:24
L7	0	((contactless contact-less) adj3 power adj3 (transmission transmitting convert$3) ((inductive magnetic) adj2 coupl$3) ((rotatory rotational) adj2 (convert$3 transform$3))) and (lc resonan$2) near5 (primary static stationary fixed steady stator) same (switch transistor mosfet mos fet cmos) near5 (secondary mov$3 rotating rotational rotates rotor rotary) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:26

L8	6	(plane airplane aircraft helicopter) and (contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:54
L9	8	(plane airplane aircraft helicopter vehicle automobile automotive truck train) and (contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:57
L10	8	(plane airplane aeroplane aircraft helicopter vehicle automobile automotive truck train motorcycle) and (contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 11:58
L11	8	(plane airplane aeroplane aircraft helicopter vehicle automobile automotive truck train motorcycle tractor transport$3 bus) and (contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:02
L12	0	(airplane aeroplane aircraft helicopter) same ((contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) (rotary adj transformer)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:05
L13	4	(piezo piezoelectric (capacit $4 near2 (actuator coul$3))) same ((noncontact$3 (non adj contact$3) contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) (induct$3 adj coupl$3) (transformer near rotatory)) and (static stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor rotary) and	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:08

		@pd>="20080202"				
L14	0	(((piezo piezoelectric) adj2 actuator)) same ((noncontact$3 (non adj contact$3) contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) (induct$3 adj coupl$3) (transformer near rotatory)) and (static stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor rotary) and (aircraft airplane aeroplane vehicle automobile automotive automotor) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:10
L15	14	((piezo piezoelectric) adj2 actuator) and (aircraft airplane aeroplane) same wing and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:11
L16	0	((piezo piezoelectric) adj2 actuator) and ((rotary adj wing) helicopter) and ((contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) (rotary adj transformer)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:13
L17	9	((piezo piezoelectric) adj2 actuator) and ((rotary adj wing) helicopter) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:13
L18	0	((rotary adj wing) helicopter) and ((contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) (rotary adj transformer)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:14
L19	0	((piezo piezoelectric) adj2 actuator) same positive same negative same (half-wave halfwave (half adj wave)) same control$4 and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:15

L20	1	((piezo piezoelectric) adj2 actuator) same (half-wave halfwave (half adj wave)) same control$4 and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:16
L21	28	((piezo piezoelectric) adj2 actuator) near10 (transformer isolat$3 ((magnet$3 induct$4) adj coupl$3)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:17
L22	0	((piezo piezoelectric) adj2 actuator) same (scr thyristor) same parallel same diode and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:19
L23	0	((piezo piezoelectric) adj2 actuator) near10 (transformer isolat$3 ((magnet$3 induct$4) adj coupl$3)) same (thyristor scr) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:40
L24	6	((piezo piezoelectric) adj2 actuator) near10 (transformer isolat$3 ((magnet$3 induct$4) adj coupl$3)) same (thyristor scr switch$3 (charg$3 near10 discharg$3)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:42
L25	0	((piezo piezoelectric) adj2 actuator) same unidirectional near2 switch $3 and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:45
L26	0	((piezo piezoelectric) adj2 actuator) same (scr thyristor unidirectional) same (switch $3 semiconductor) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:46
L27	2	((piezo piezoelectric) adj2 actuator) same (scr thyristor unidirectional) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:47

L28	6	(piezo piezoelectric) same ((unidirectional and bidirectional) (unipolar same bipolar) ((scr thyristor) same triac)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:51
L29	2	((stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor) (rotatory near2 transformer)) and (piezo piezoelectric) same ((unidirectional same bidirectional) (unipolar same bipolar) ((scr thyristors) same triac)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 12:55
L30	0	((stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor) (rotatory near2 transformer)) and ((piezo piezoelectric) same (scr thyristors) same triac) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 13:00
L31	0	converter and ((piezo piezoelectric) same (scr thyristors) same triac) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 13:01
L32	16	((piezo piezoelectric) same (bipolar npn pnp scr thyrsitors triac) same (fet mosfet mos cmos nmos pmos c-mos p-mos n-mos)) and @pd>="20080202"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/06 13:02
S1	10	("5798622" "6934167" "6231013" "07046864" "7046864").pn.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 11:48
S2	4	"542638".ap.	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 14:29

S3	10	307/75.ccls. and @pd>="20080203"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 14:56
S4	9	(contactless contact-less) adj power adj (transmission transmitting) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 15:02
S5	0	(contactless contact-less) adj2 power adj2 (transmission transmitting) and transformer and (stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor) and frequency and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 15:04
S6	0	(contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and transformer and (stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor) and frequency and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 15:05
S7	0	(contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and transformer and (stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor rotary) and frequency and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 15:05
S8	0	((contactless contact-less) adj2 power adj2 (transmission transmitting convert$3) and transformer) same (static stationary fixed steady stator) same (mov$3 rotating rotational rotate rotor rotary) same frequency same capacit$4 and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 15:06

S9	1	(contactless contact-less) adj2 (power energy) adj2 (transmission transmitting convert$3) and transformer and (static stationary fixed steady stator) same (mov$3 rotating rotational rotates rotor rotary) and frequency and capacit$4 and (switch transistor semiconductor bipolar mosfet fet mos cmos) and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 15:07
S10	8	307/45.ccls. and @pd>="20080201"	US-PGPUB; USPAT; USOCR; FPRS; EPO; JPO; DERWENT; IBM_TDB	OR	ON	2008/08/05 15:11

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